

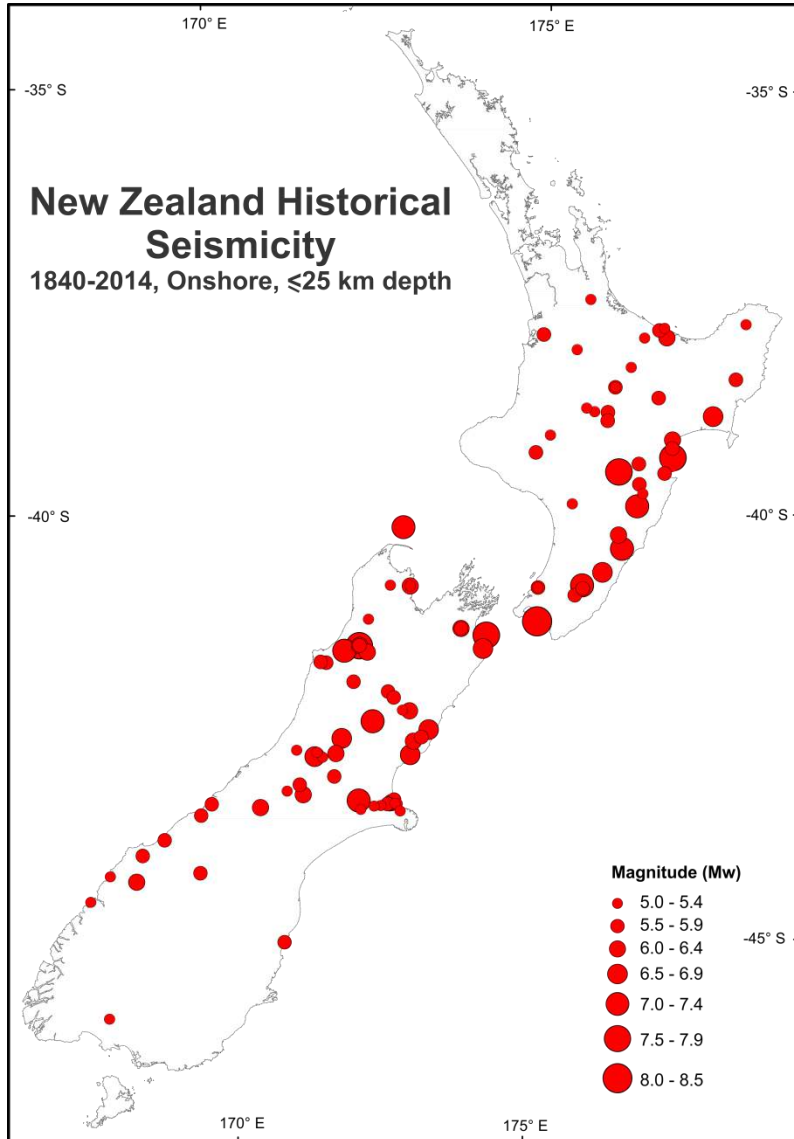
EARTHQUAKE SIMULATOR RESEARCH – WEBINAR

9 March 2021

Presentation Outline

- 1) Why virtual earthquakes?
- 2) Virtual earthquake generation
- 3) Earthquake and fault interactions

The Earthquake Information Problem



Seismic hazard information is typically derived from historical and prehistorical earthquakes.

The NZ historical earthquake record of ~180 yrs is very short by geological standards.

~20 historical earthquakes $> M7$

We only have good prehistoric earthquake information for ~50 of ~900 known active faults (~5%).

200-300 prehistorical earthquake

NZ experienced 100,000-500,000 $>M7$ earthquakes in last 1 Myrs

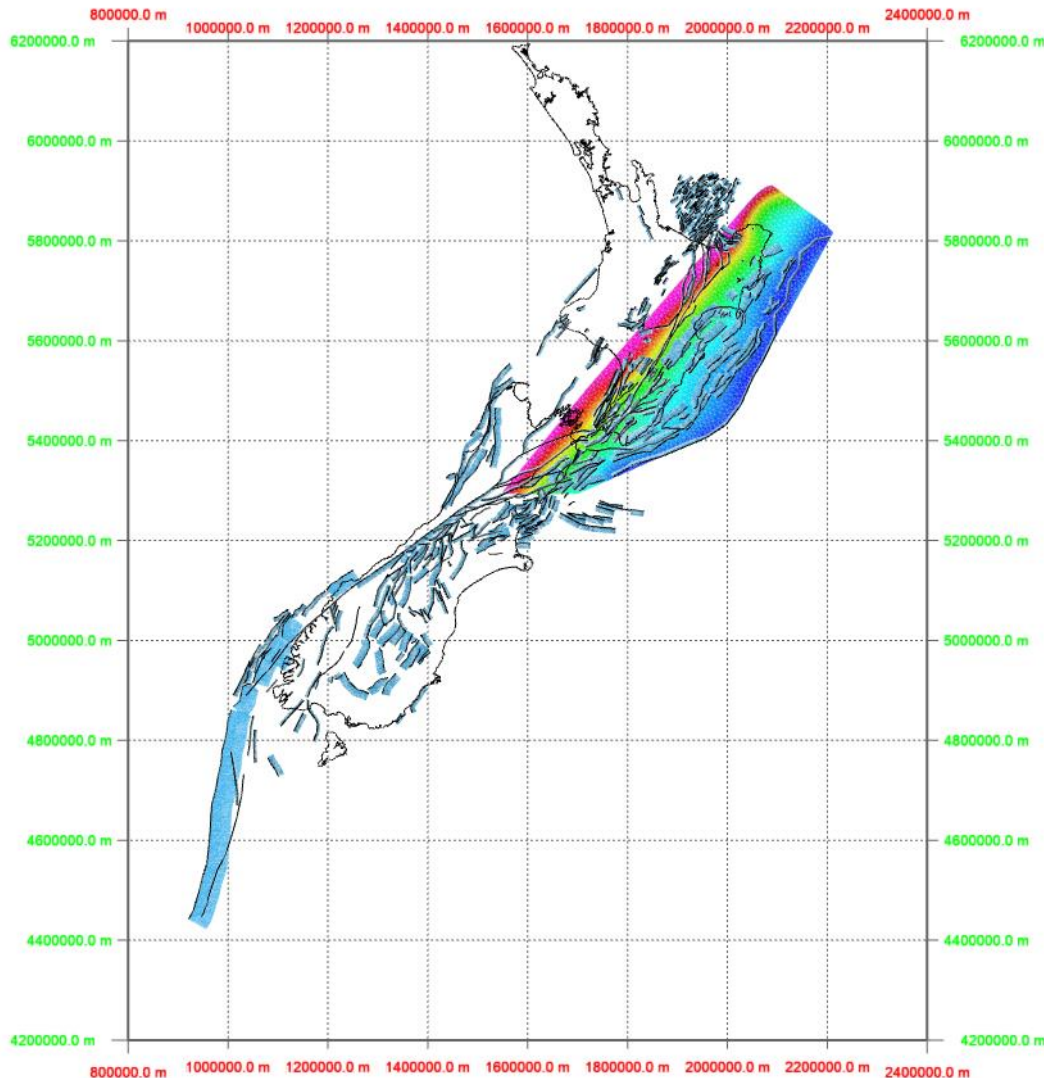
Solving the earthquake information problem

Develop physics-based models of virtual earthquakes enabling new avenues of research to assess and forecast a range of earthquake-related hazards.



Kaikōura Earthquake fault rupture (photo Kate Pedley)

What is an Earthquake Simulator?



NZ Fault Source model (2020)

Physics-based computer model that approximates earthquake processes.

Uses information from known faults (e.g., location, size, slip rate).

Assign model rock and fault properties.

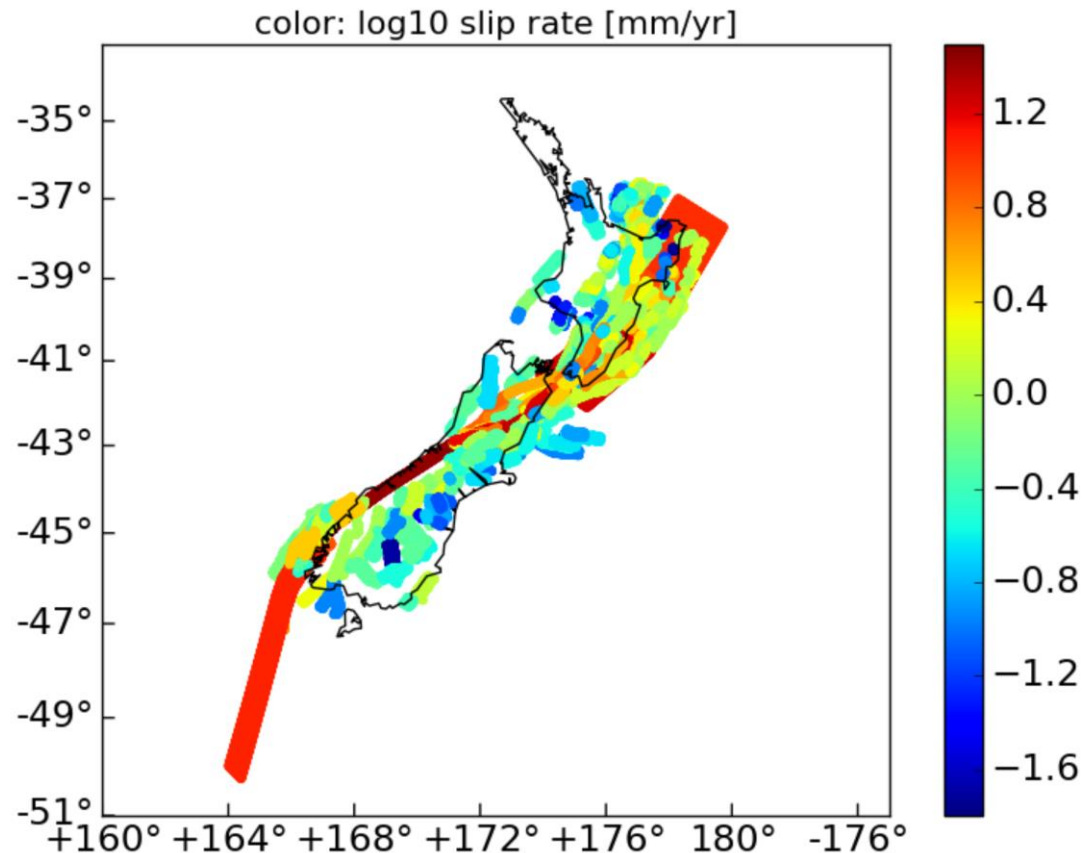
Model stresses faults and tracks resulting earthquakes.

Model can be used for 100s of faults and millions of years.

NZ model uses RSQSim software (Richards-Dinger & Dieterich, 2012).

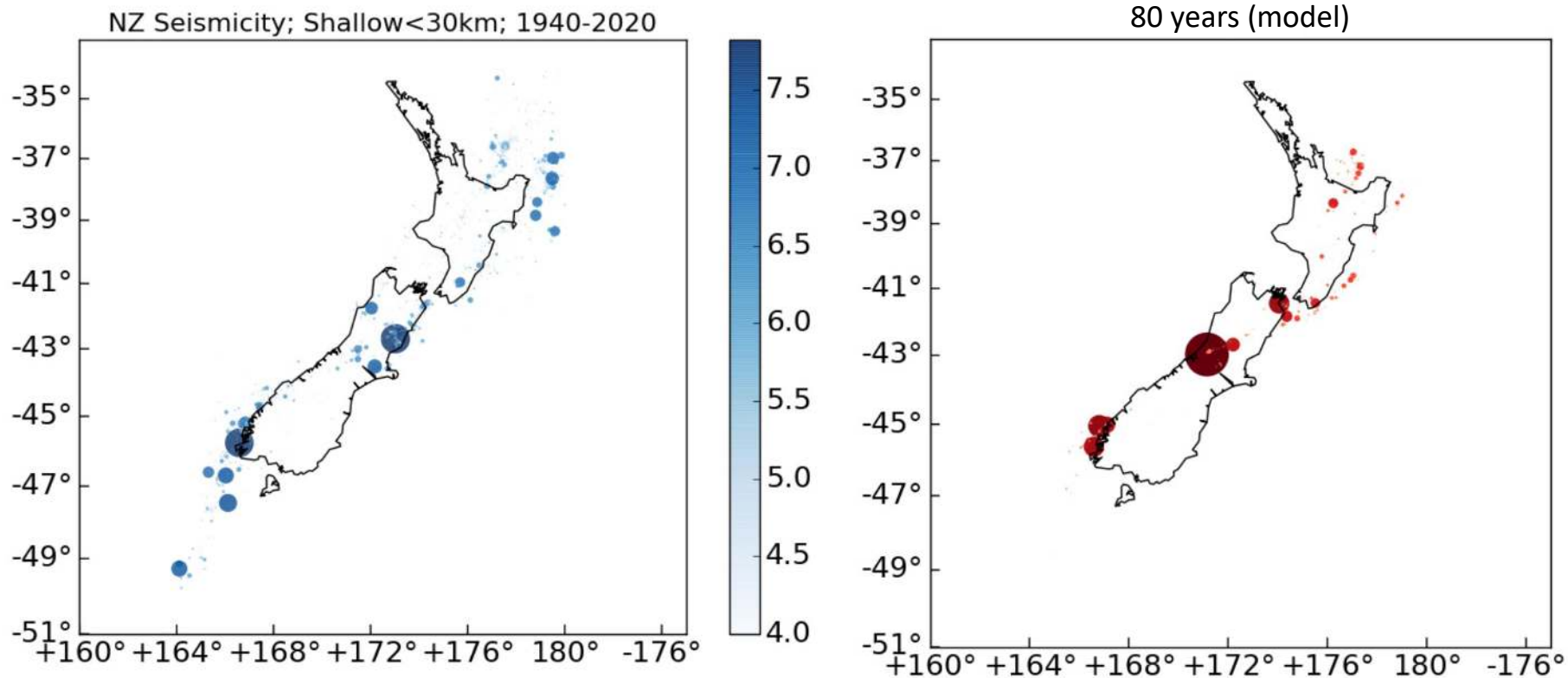
New Zealand Virtual Earthquake Model

- RSQSim model running for NZ (Shaw et al. preprint).
- Initial simulator model uses faults from Stirling et al. (2012).
- New Zealand fault model revised and updated (new model includes >900 faults – 70% increase from previous model).



Shaw et al. (preprint)

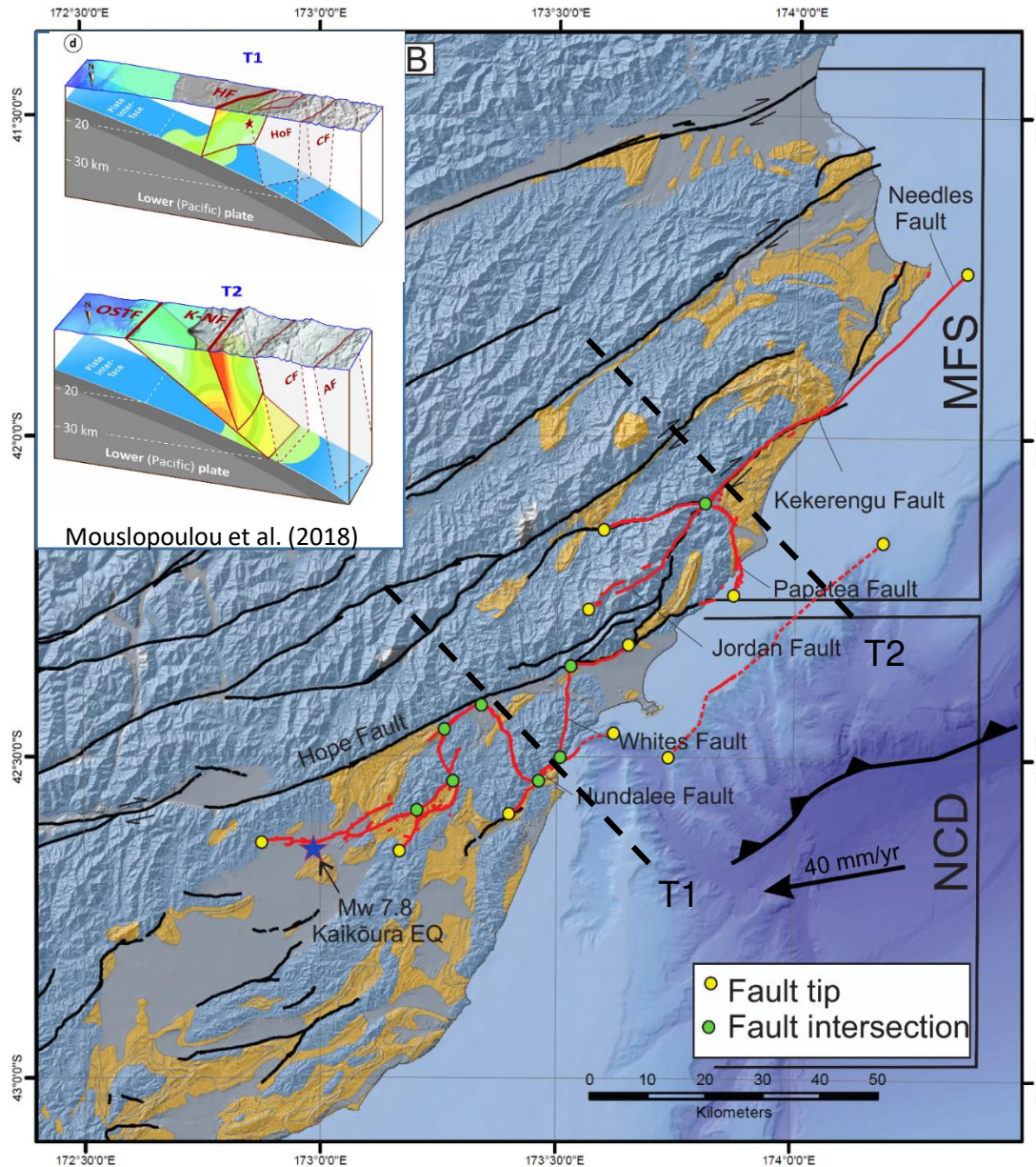
Comparison observations and model



Shaw et al. (preprint)

Broad earthquake patterns from simulator show many similarities to historical earthquakes.

Kaikōura Earthquake – multiple faults



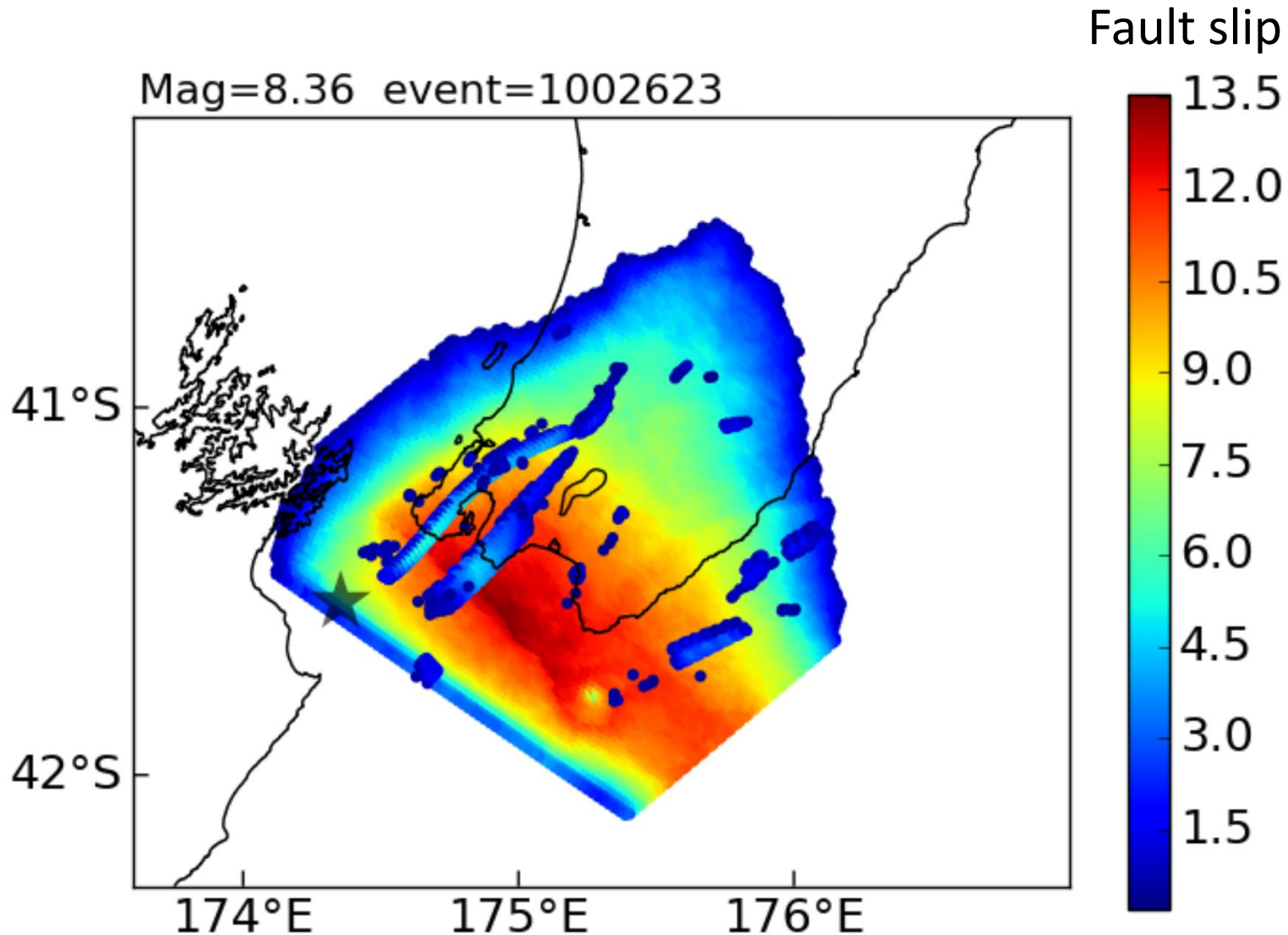
Mouslopoulou et al. (2018)

Modified from Nicol et al. (2018)

Multi-fault ruptures are common in the NZ historical earthquake record.

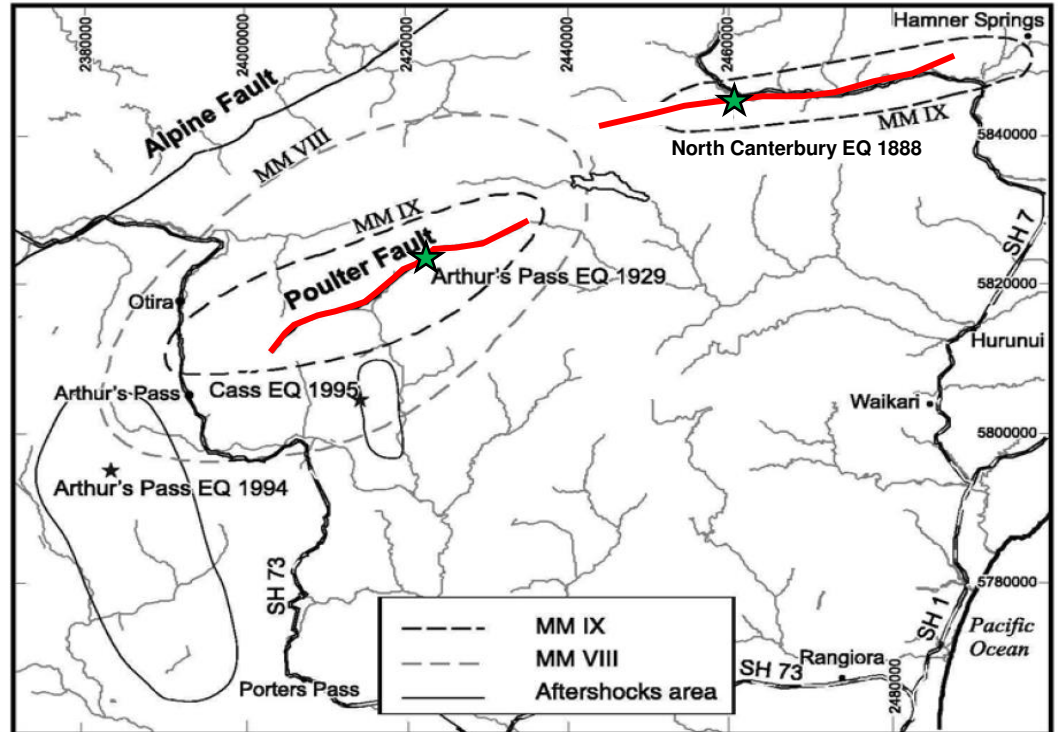
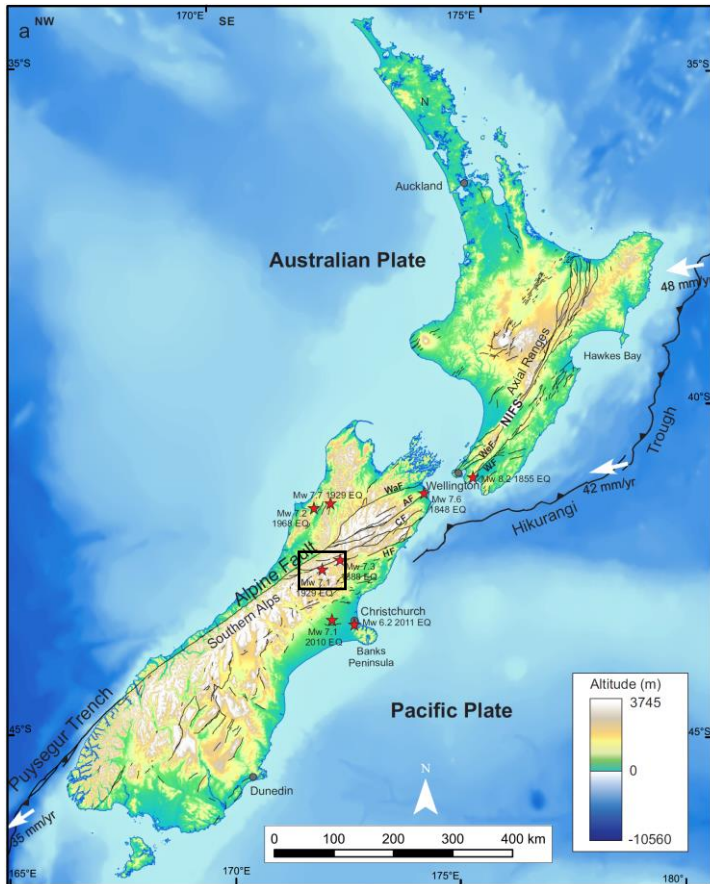
Are they common in our virtual earthquake record?

Multi-fault virtual earthquakes



Shaw et al. (preprint)

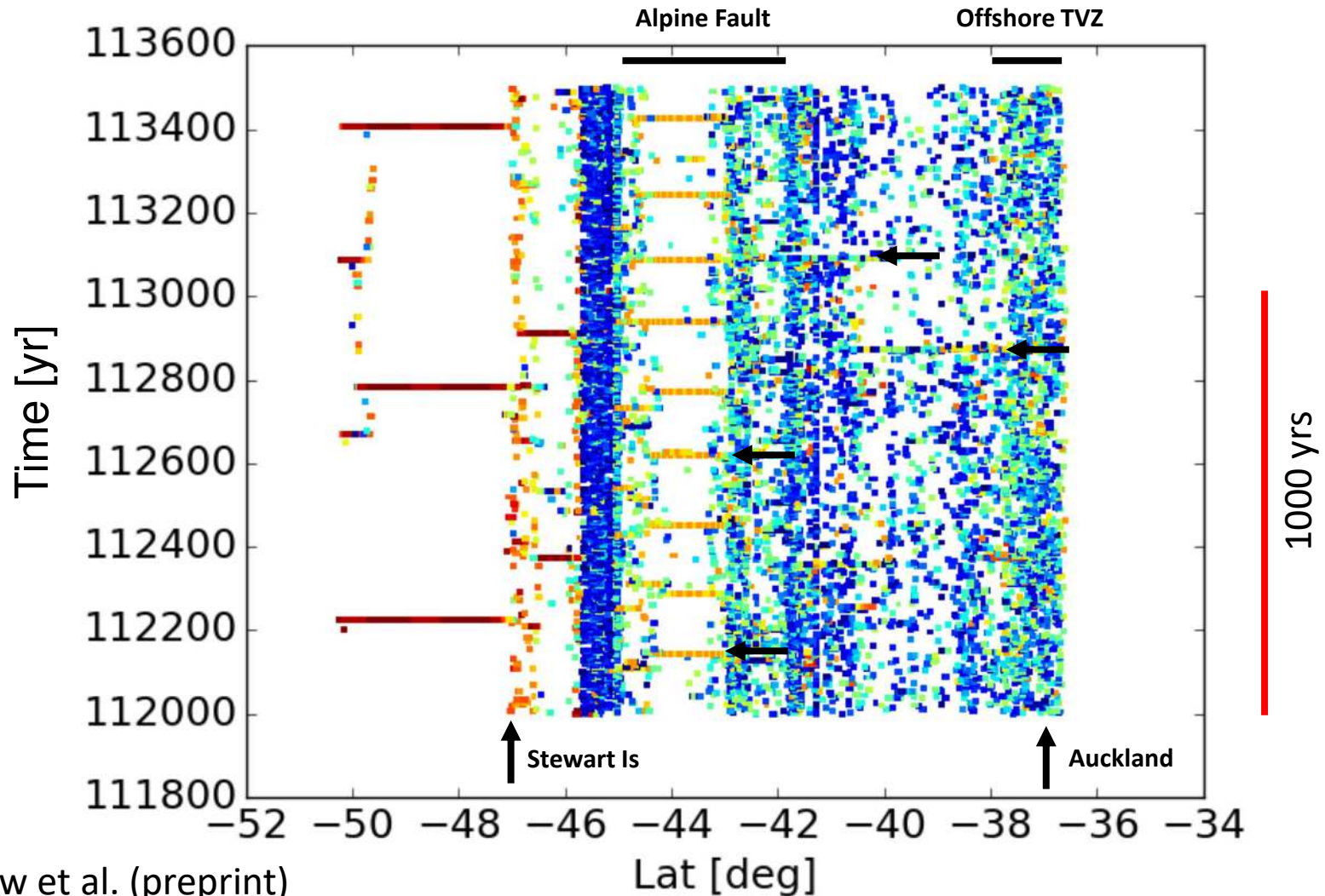
Earthquake triggering – Observations



Modified from Berryman and Villamor (2004)

Some historical large magnitude earthquakes appear to have triggered large earthquakes.

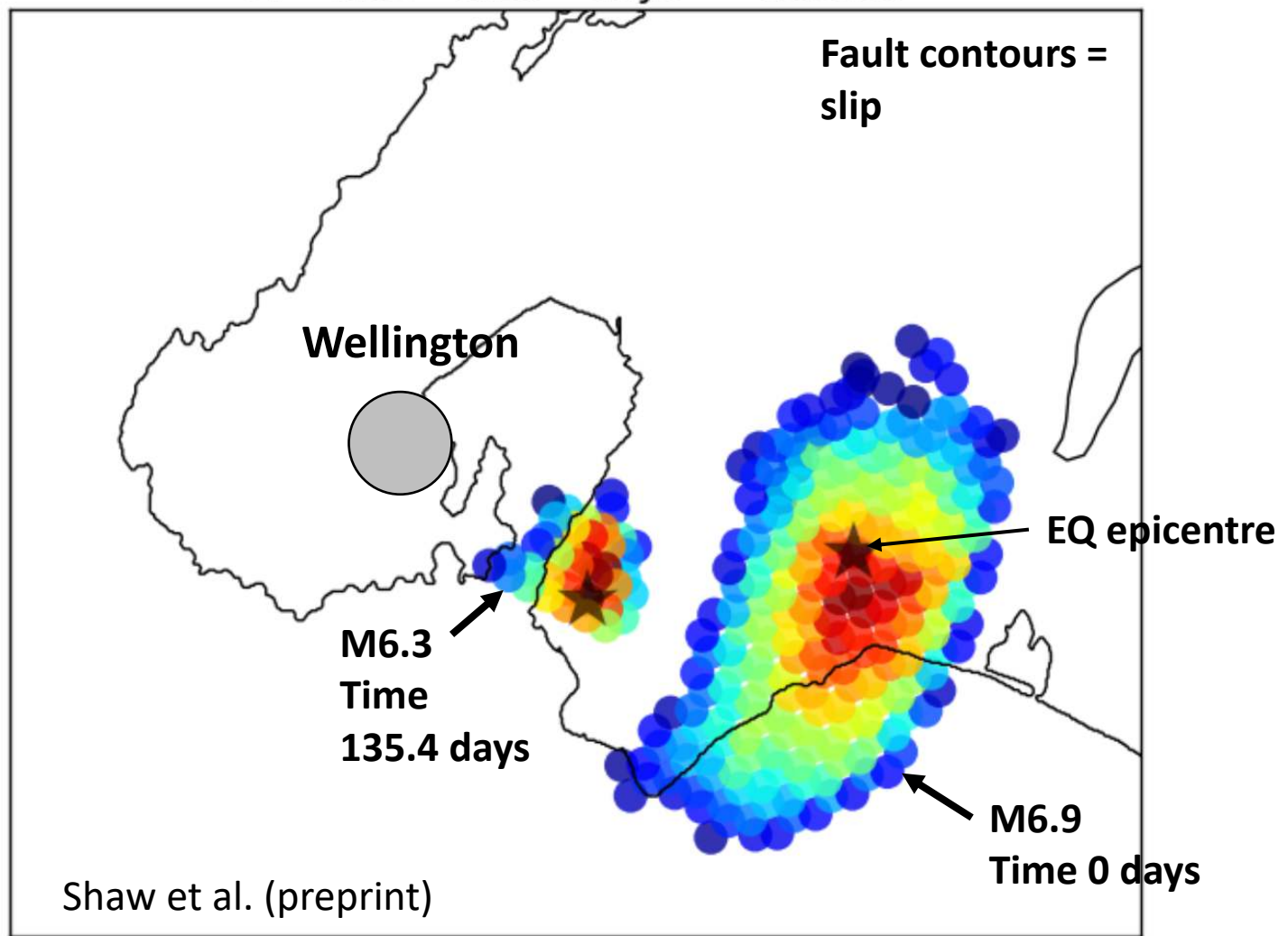
Earthquake triggering - Model



Shaw et al. (preprint)

Model shows some spatially stable earthquake activity
Horizontal alignment of events consistent with triggering

Earthquake triggering - Model



Earthquake triggering common in the model.
Model can be interrogated to determine requirements for triggered events.

Concluding remarks

Initial RSQSim earthquake simulator model has been developed for NZ (Shaw et al. preprint).

Virtual earthquakes share many similarities with historical and prehistorical earthquakes.

Stress interactions for virtual earthquakes produce multi-fault ruptures and earthquake triggering.

Future work will examine what factors (e.g., stress conditions, earthquake magnitude, fault geometries) lead to multi-fault ruptures and triggered earthquakes.

Dr Bill Fry, GNS Science

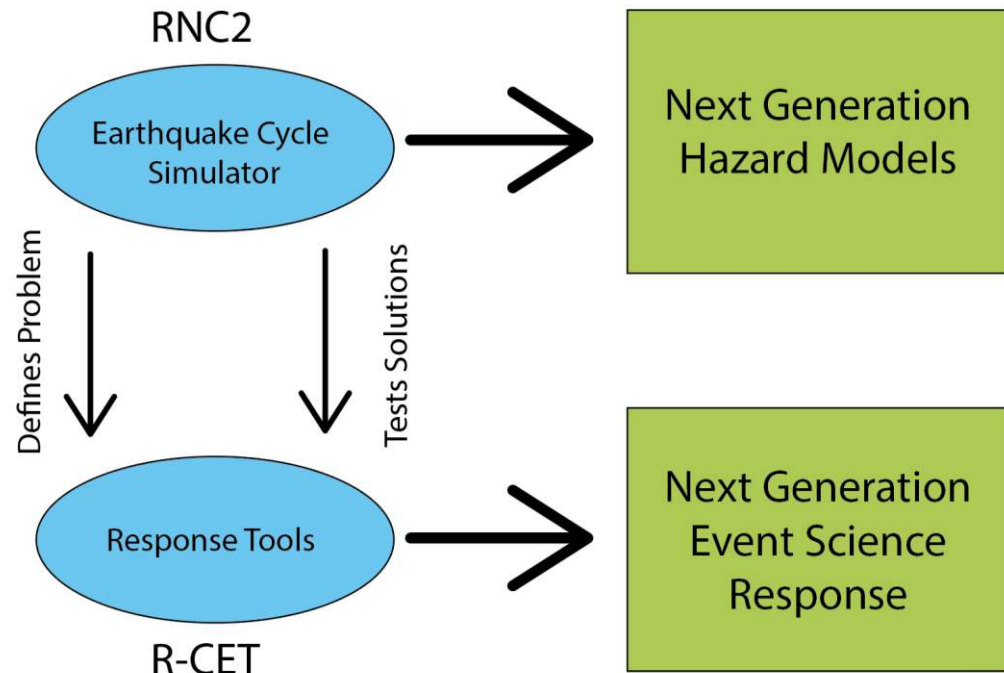
RNC2 synthetic catalogue
applications

Big Fish (Think Blue whale – 27m)

- Next generation (physics-based) seismic hazard model
- Local-source tsunami hazard model

Medium Fish (Think tohorā – 18m)

- Testing early warning (EEW and TEW)
- Improving ground motion estimates (e.g. topographic amplification)
- Improving forecasting of co- and post-seismic hazards (e.g. effects on groundwater)

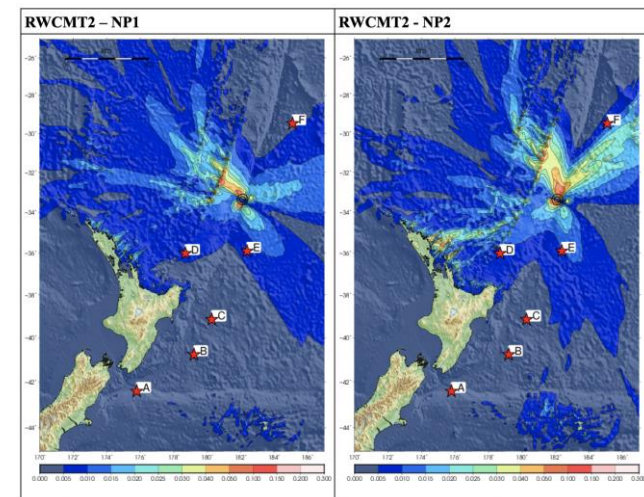
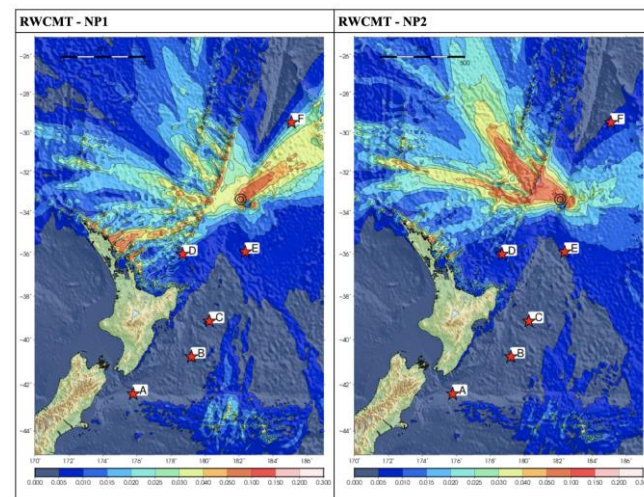
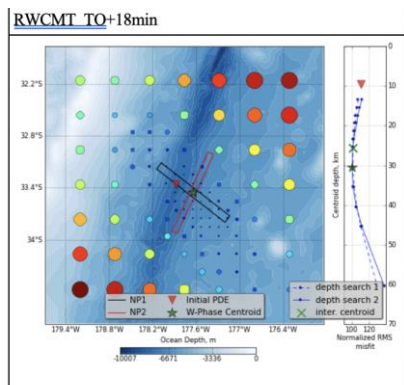
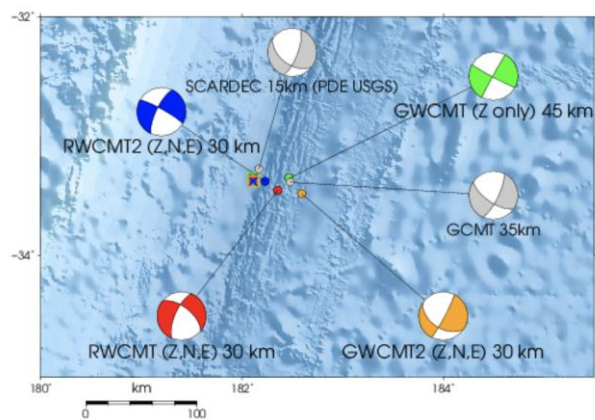
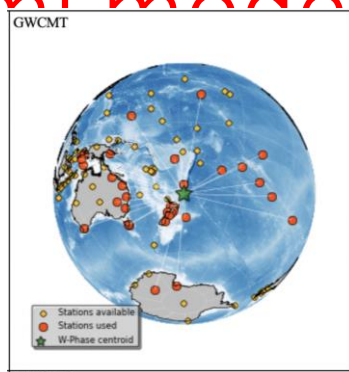


Let's take a step back to understand
TEW

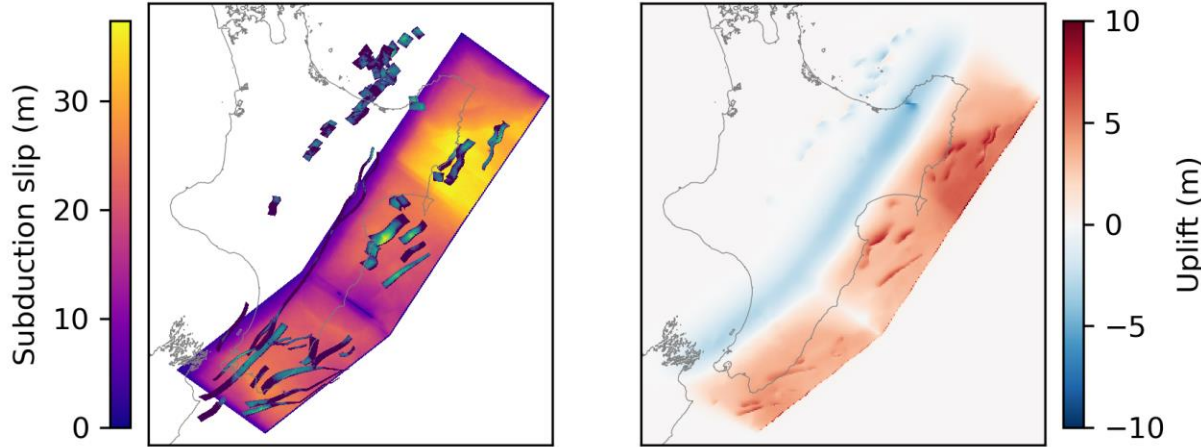
(Collaboration with C. Moore, D.
Arcas, J. Borrero and A. Howell)

Seismic solutions provide information about the *earthquake* source. This information is not sufficient to unambiguously define the *tsunami* source.

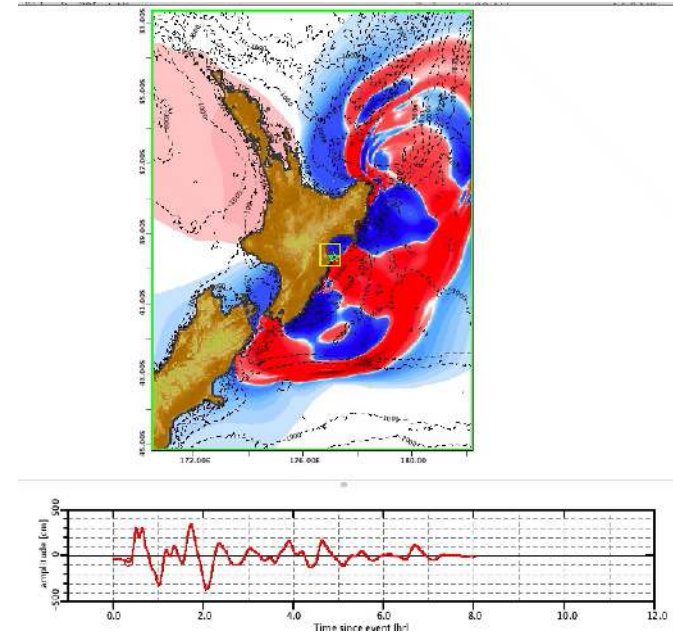
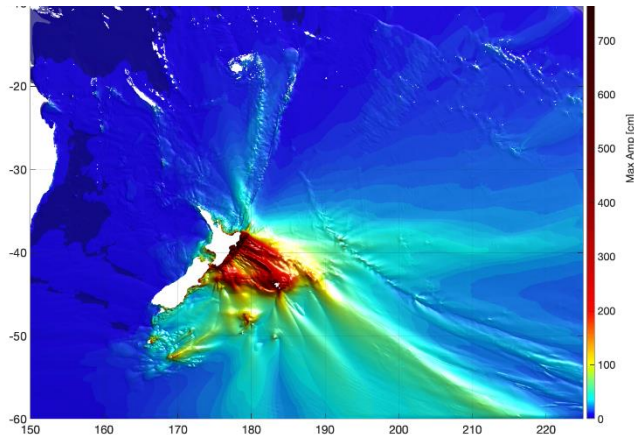
Challenge: Seismic info describes a **non-unique** tsunami model



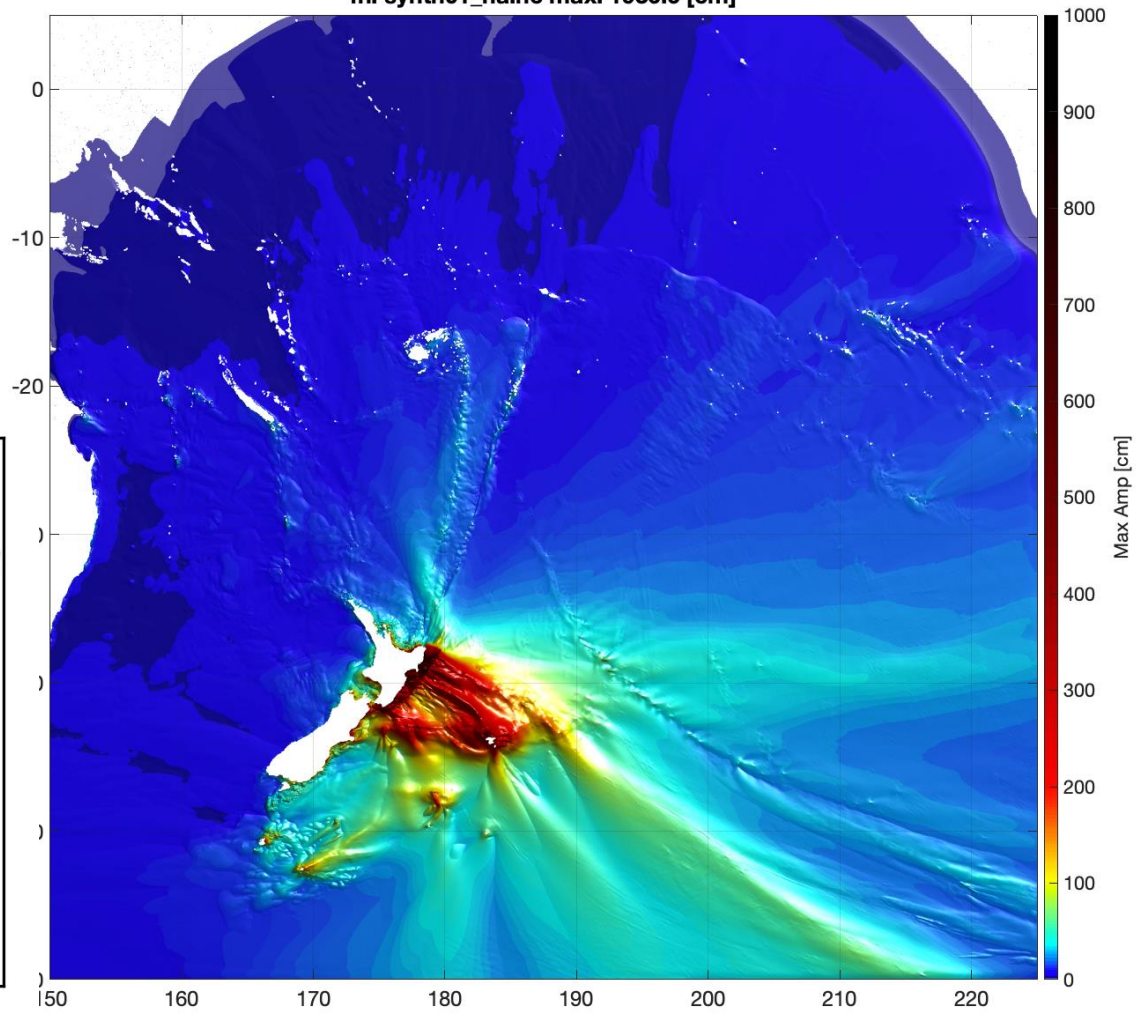
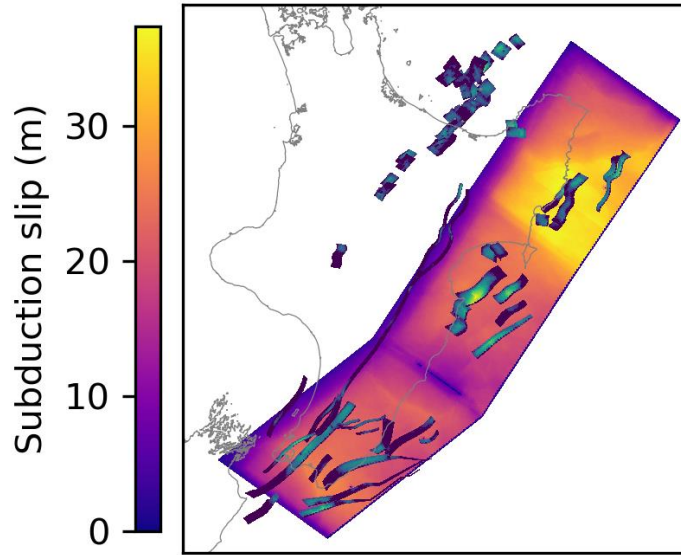
Event 32060 (Mw 9.1)



Testing TEW with a scenario event

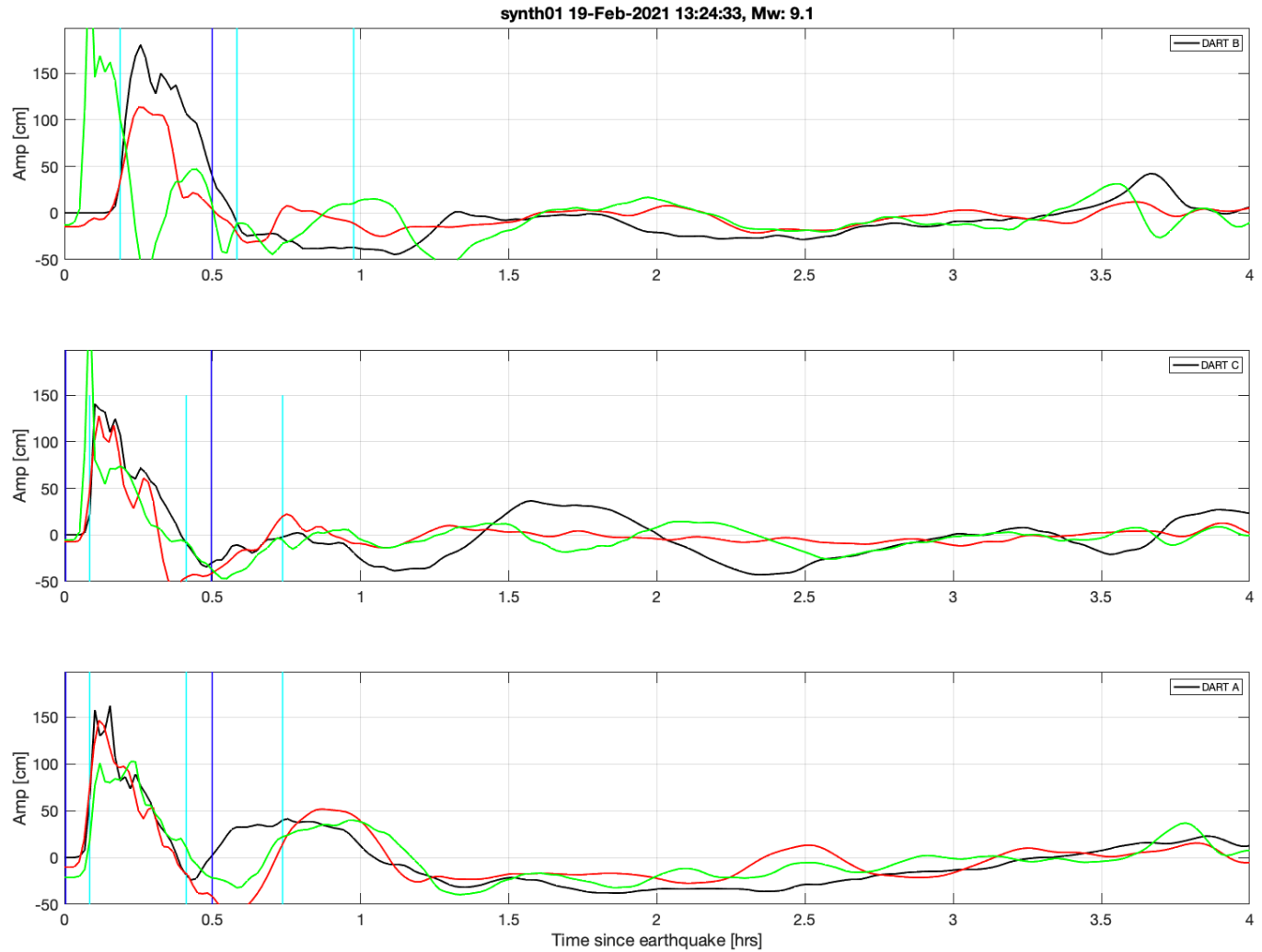


fn: synth01_ha.nc max: 1936.6 [cm]

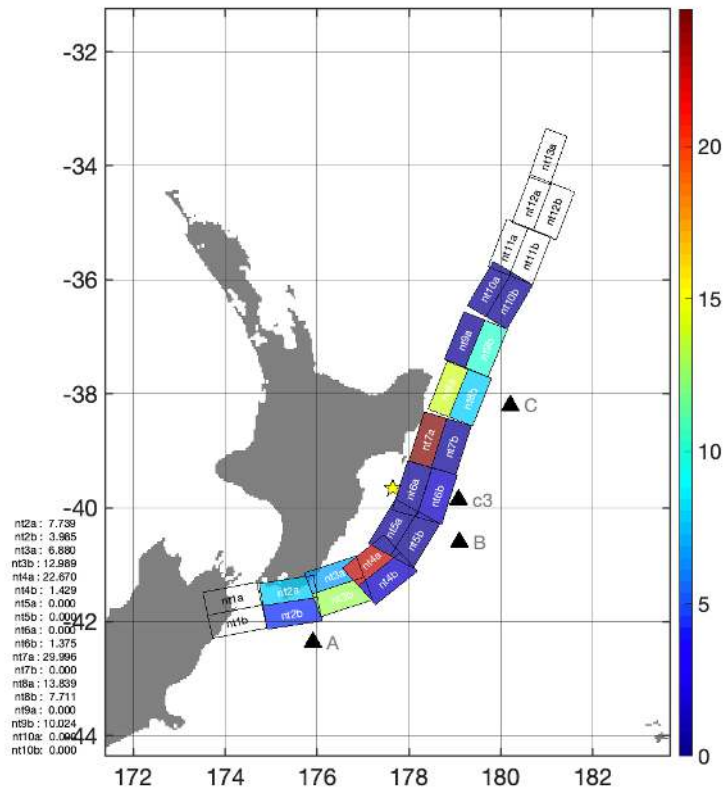


Inversion of DARTs

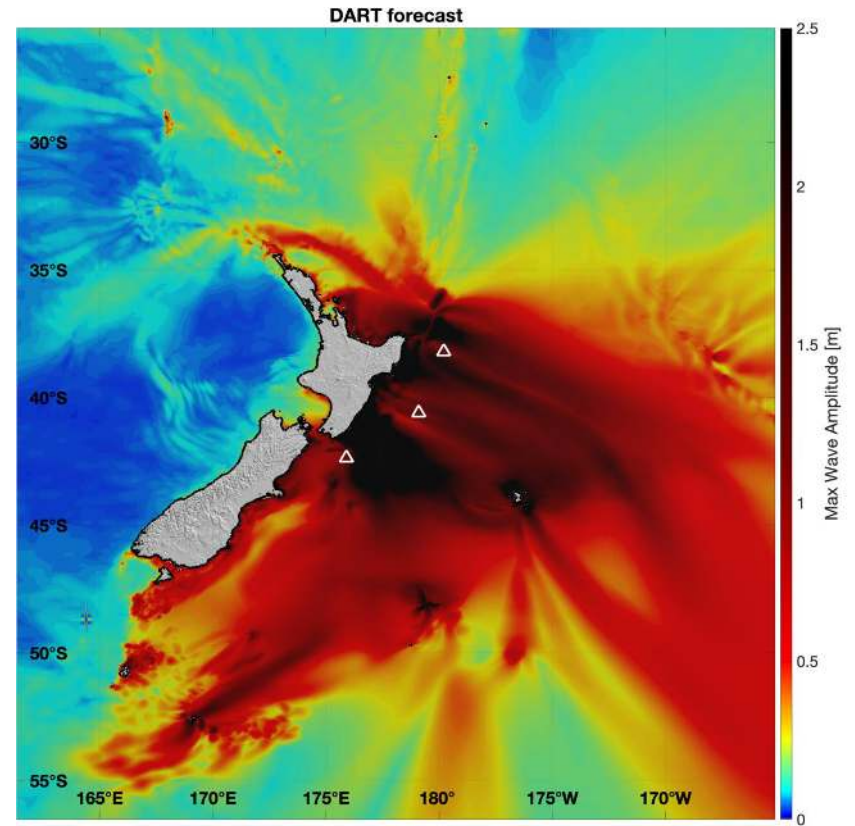
- Black: Input model
- Green: simplified model from homogeneous seismic source
- Red: inversion results



DART inversion



Forecast



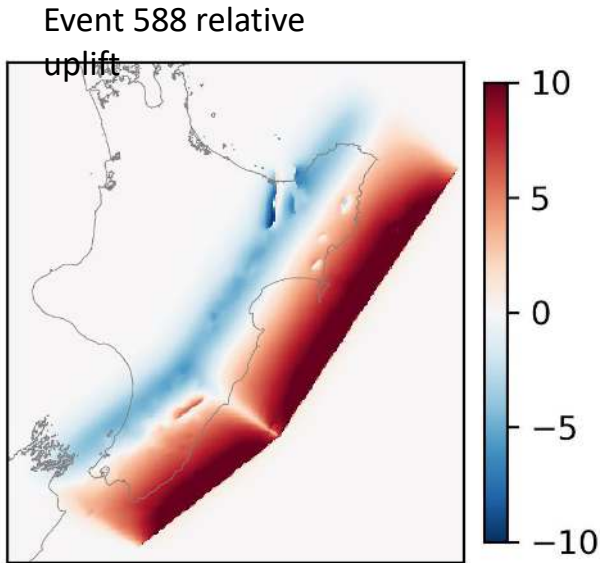
Now imagine repeating that exercise
10,000 times

- We can develop a statistical understanding of the efficacy of our early warning systems
- We can use that understanding to improve through network and algorithm adjustment

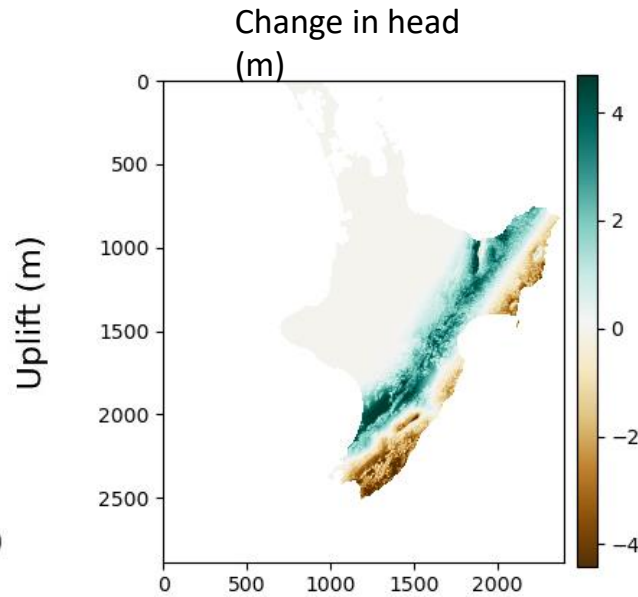
Now let's look at applications in co-seismic
groundwater changes

(Collaboration with A. Howell,
P. Johnson and R. Westerhoff)

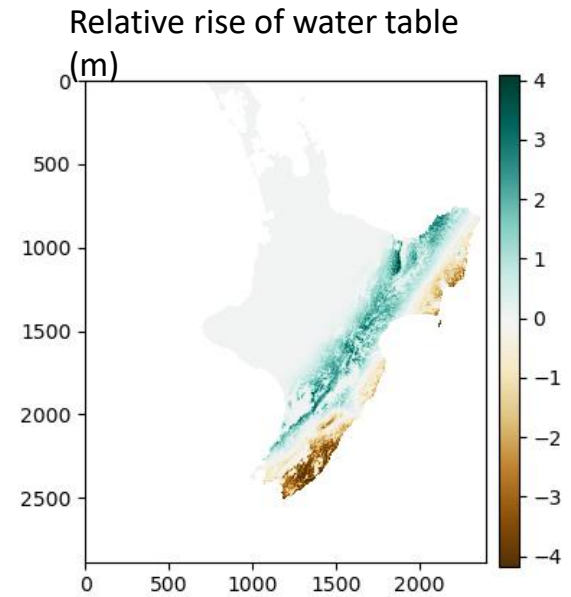
Change in water table depth: Event 588



Red: uplift
Blue: subsidence



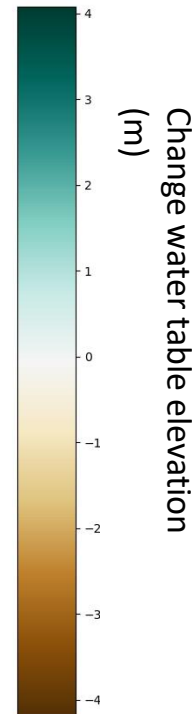
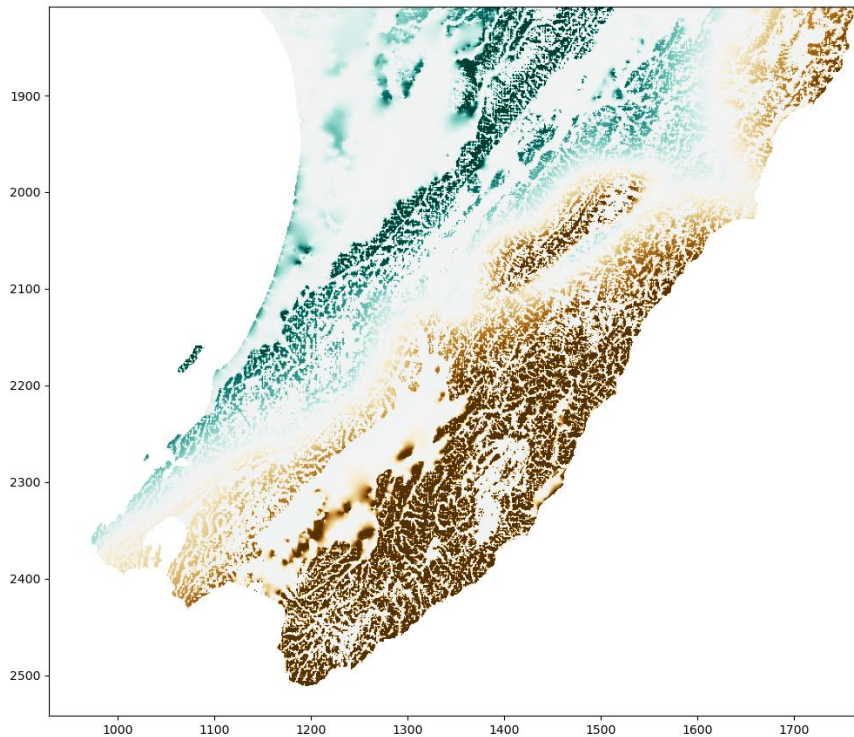
Positive value = increase in water table elevation



Positive value = shallower depth to water

All maps are on 250 m discretisation

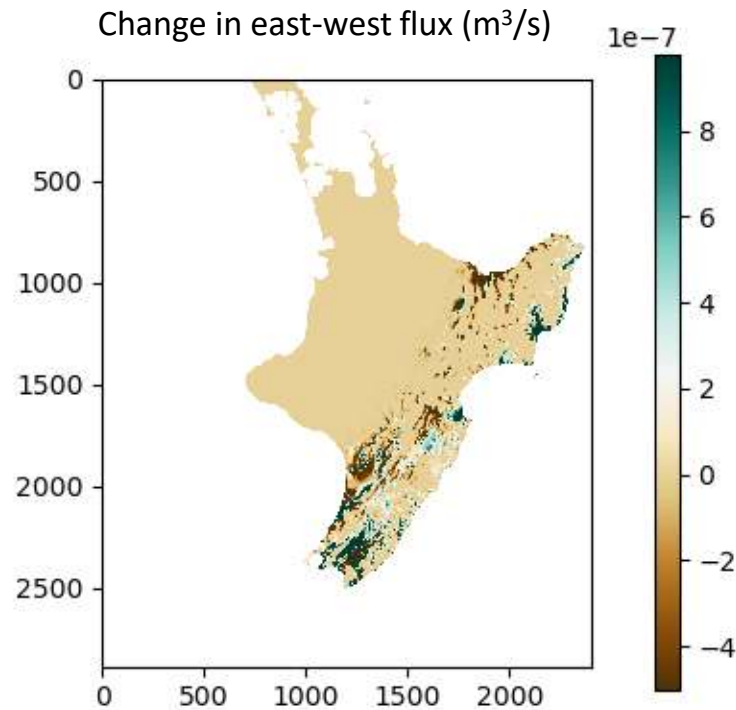
Change in water table depth: zoom view



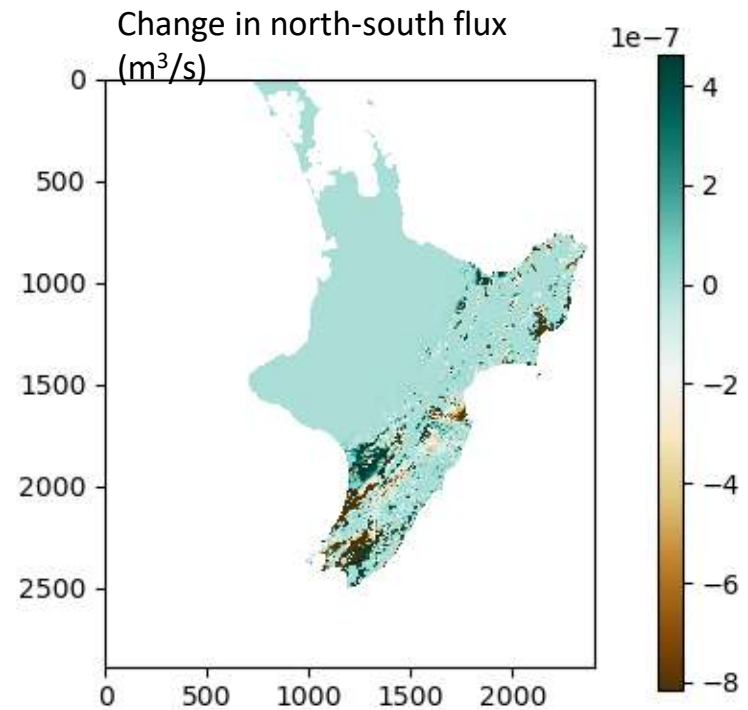
Green = water closer to land surface; possible inundation hazards, higher tendency towards flooding?

Brown: deeper to water, dry wells, reduced stream base flow

Change in groundwater flux

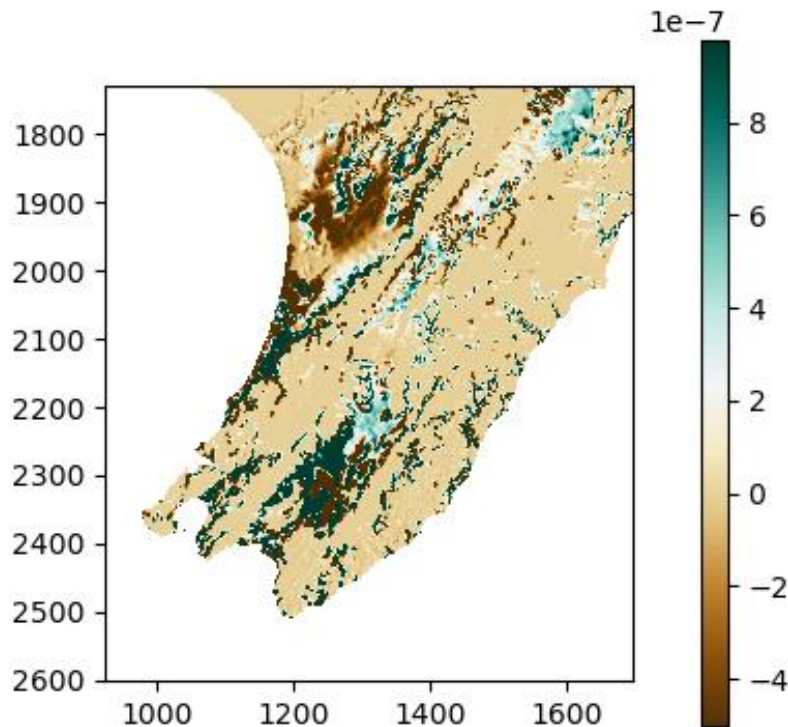


Positive values indicate increased flow to west (or reduced to east)



Positive values indicate increased flow to north (or reduced to south)

Change in E-W flux (zoom view)

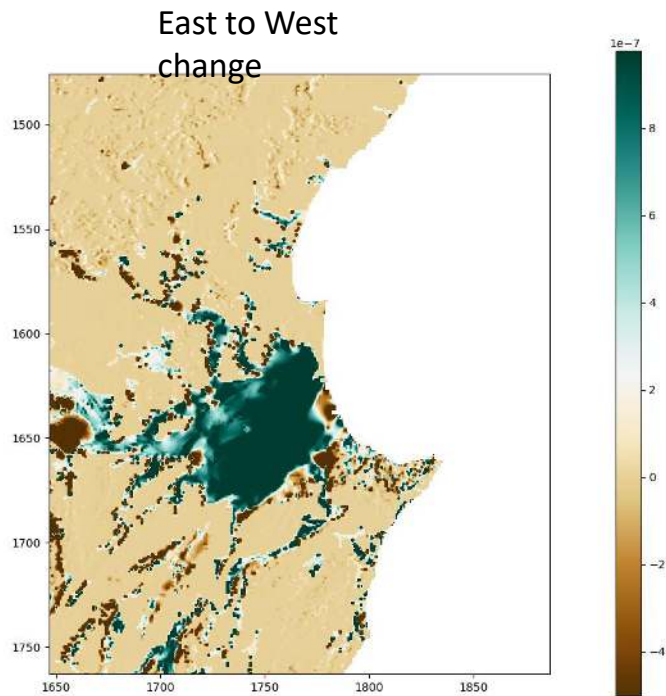


Green is greater flow to west
(or reduced to east); brown
opposite

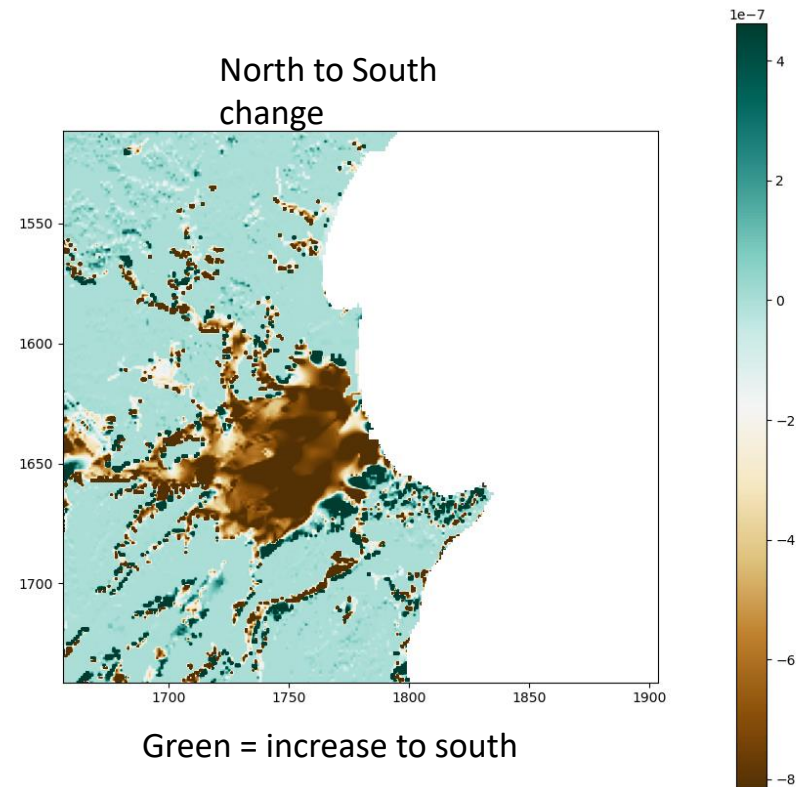
Could effect:

- Contaminant arrival time
- Drawdown at wells with pumping

Flow change: Hawke's Bay



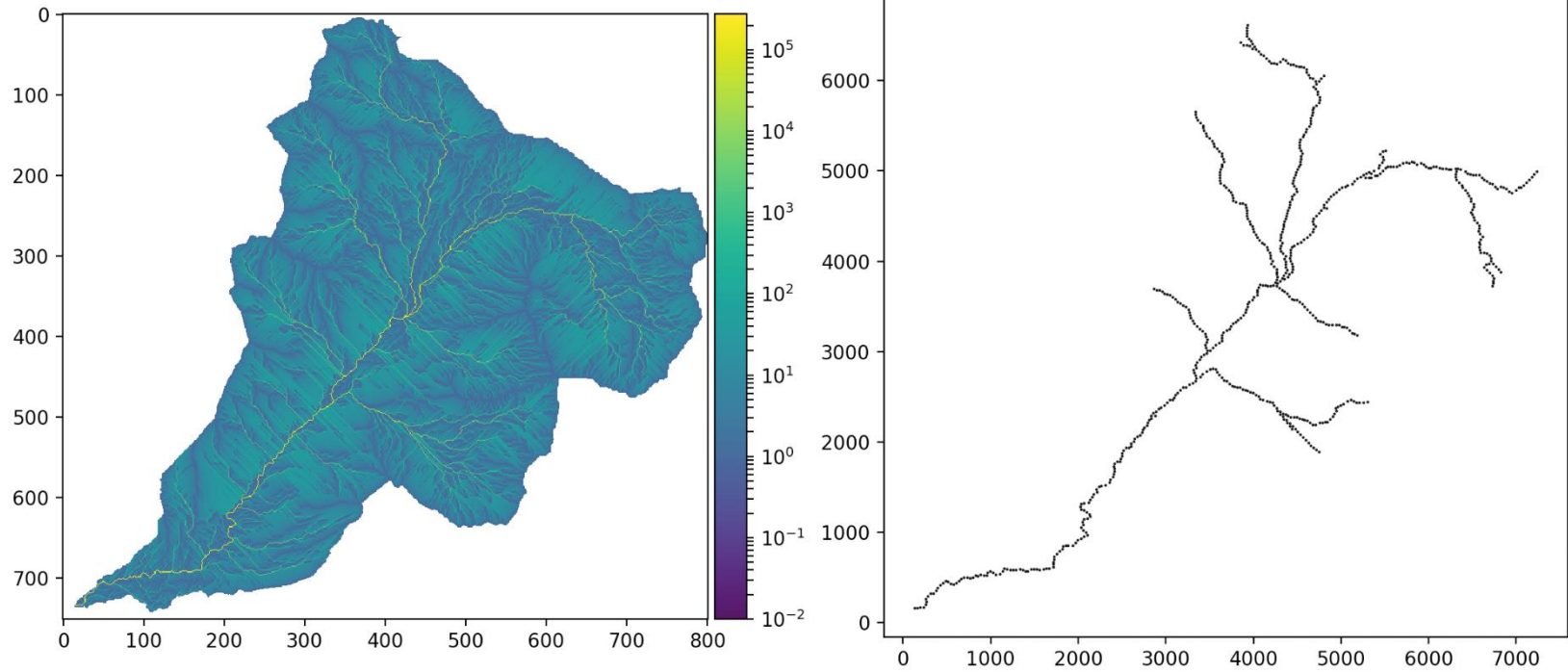
Green = increase to west



Green = increase to south

Flow accumulation

Watershed delineation (threshold: $4.500e+03$)

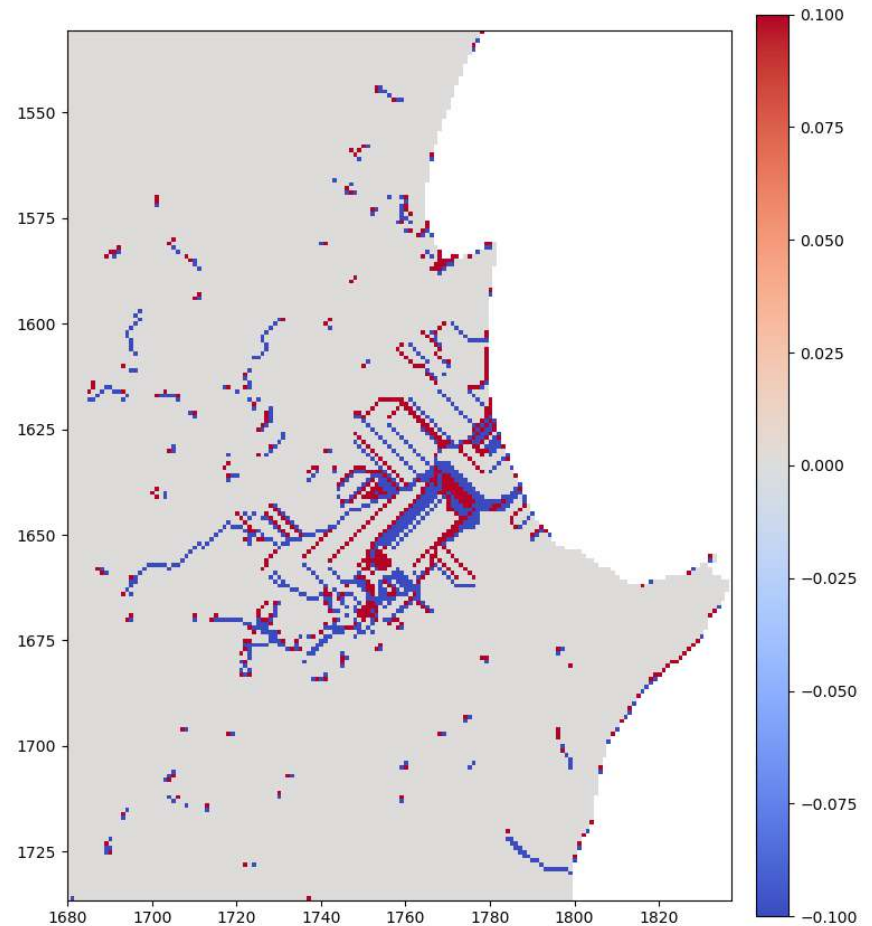


River course change – Hawke's Bay

Red: More stream accumulation
after deformation

Blue: Less stream accumulation
after deformation

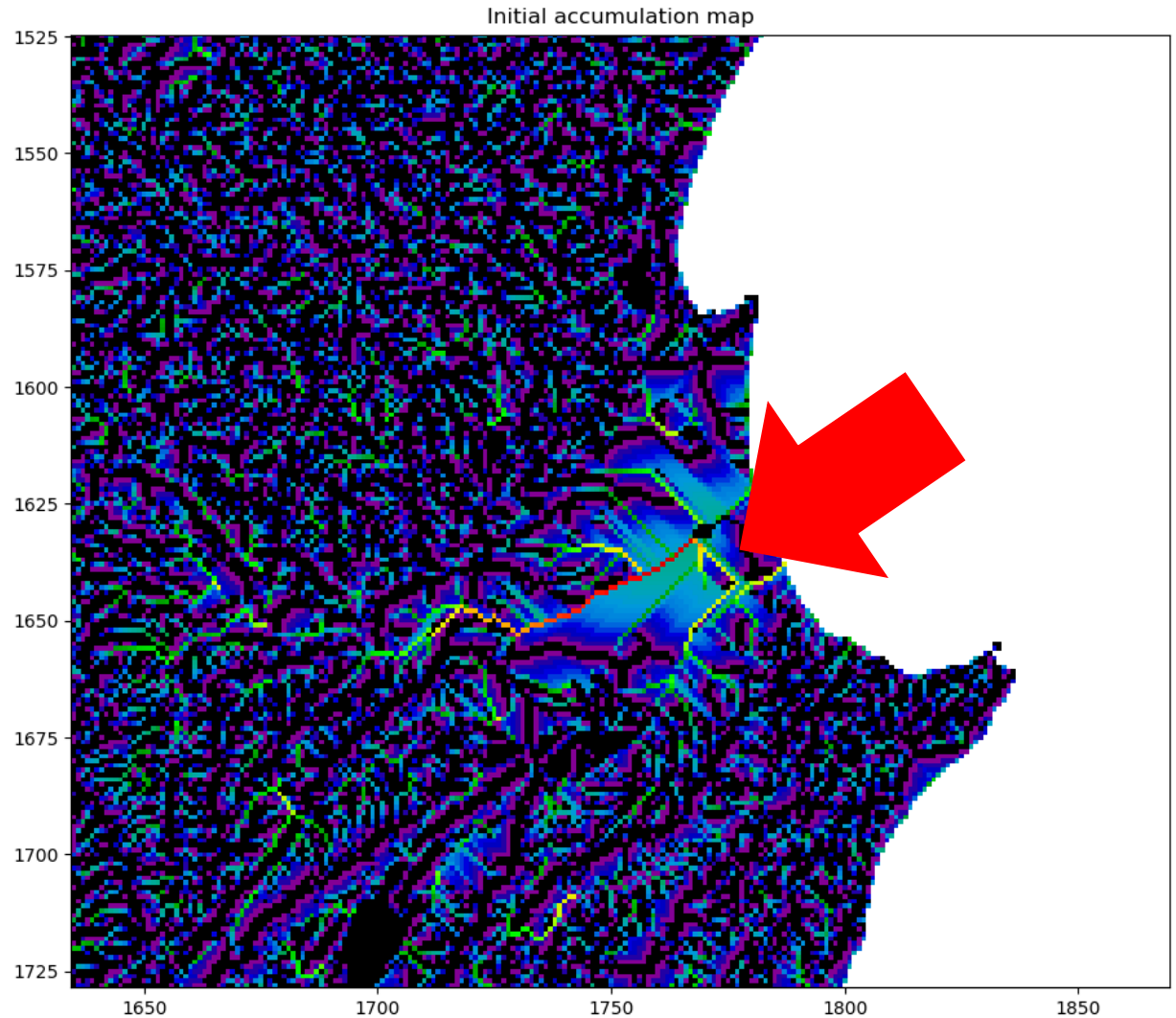
Where adjacent, stream course
will tend to change from blue
areas to red areas, presenting a
possible hazard e.g. **stress on
levees, undercutting of
infrastructure, increased flooding
hazards**, etc.



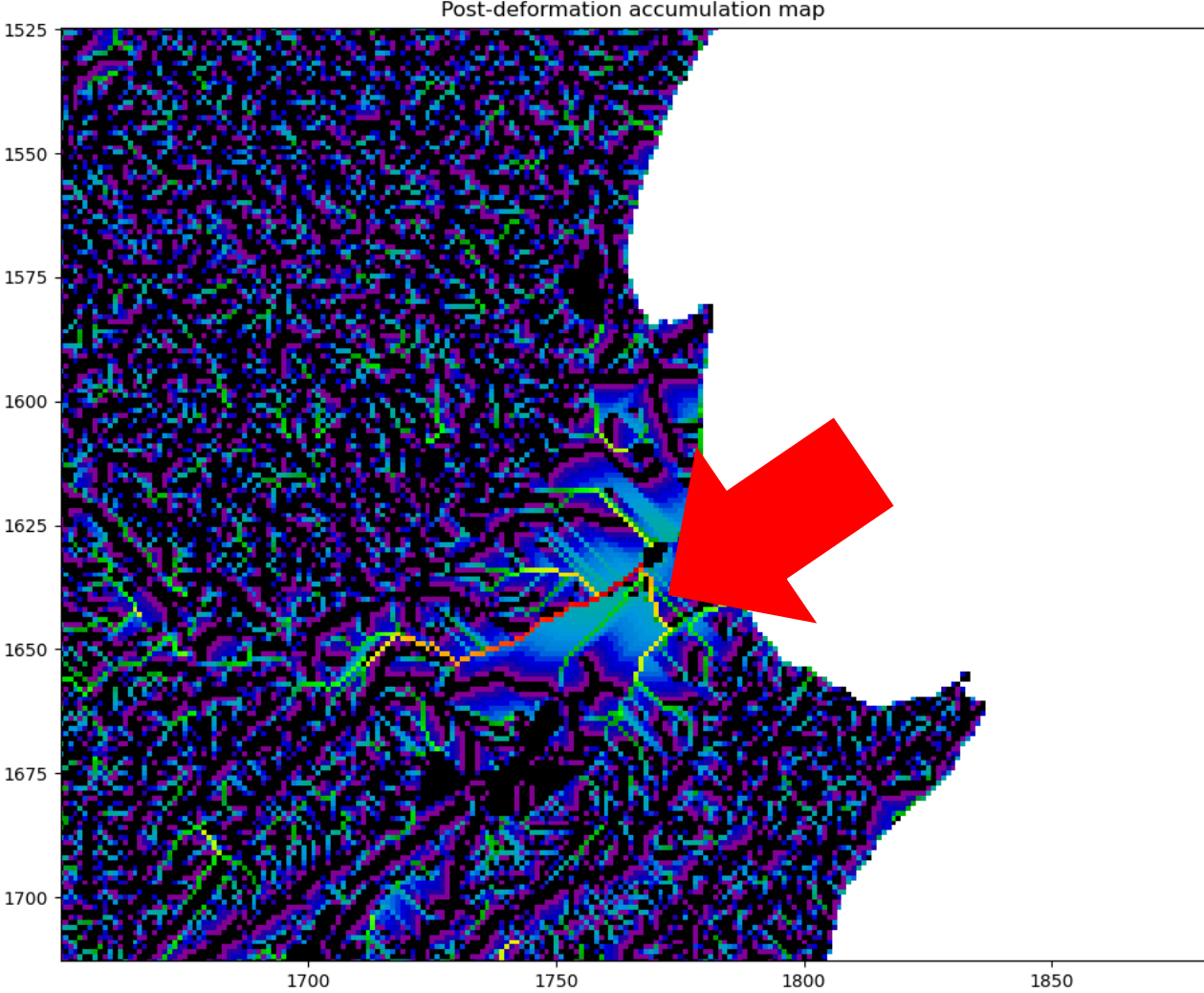
River course: Hawke's Bay

Flow

accumulation:
red colours
indicate more
drainage to
that point (i.e.,
streams);
purple/black
less



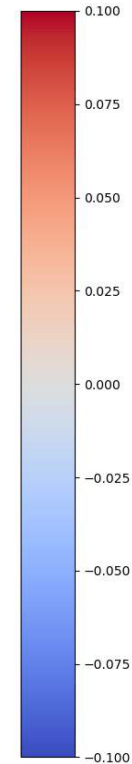
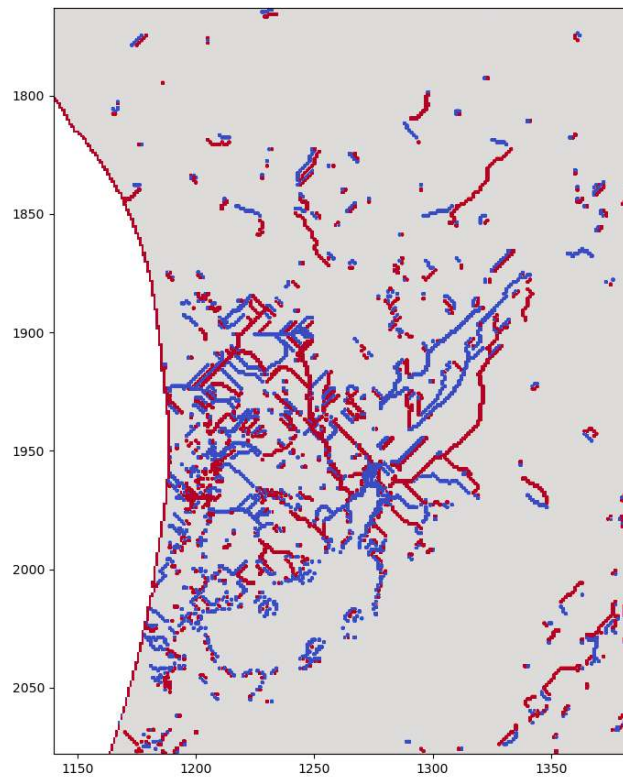
River
course:
Hawke's
Bay



Kapiti Coast: Stream change

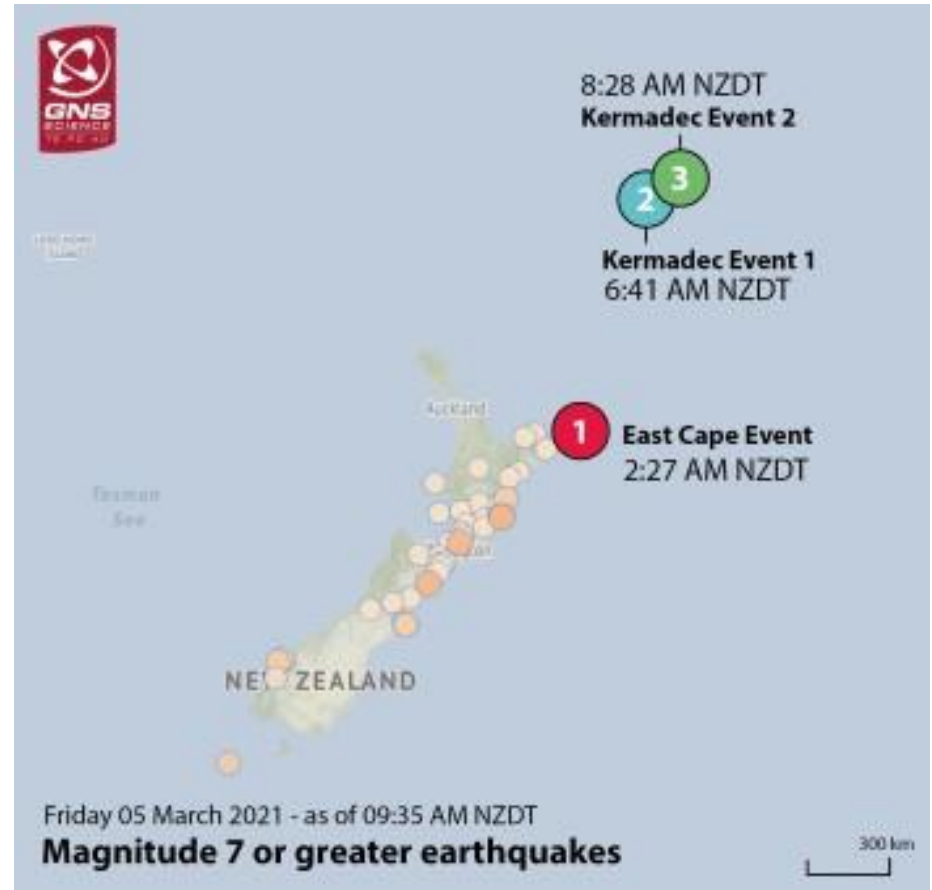
Red: More stream
accumulation after
deformation
Blue: Less stream
accumulation after
deformation

Numerous possible
stream realignments



Bonus material!!!

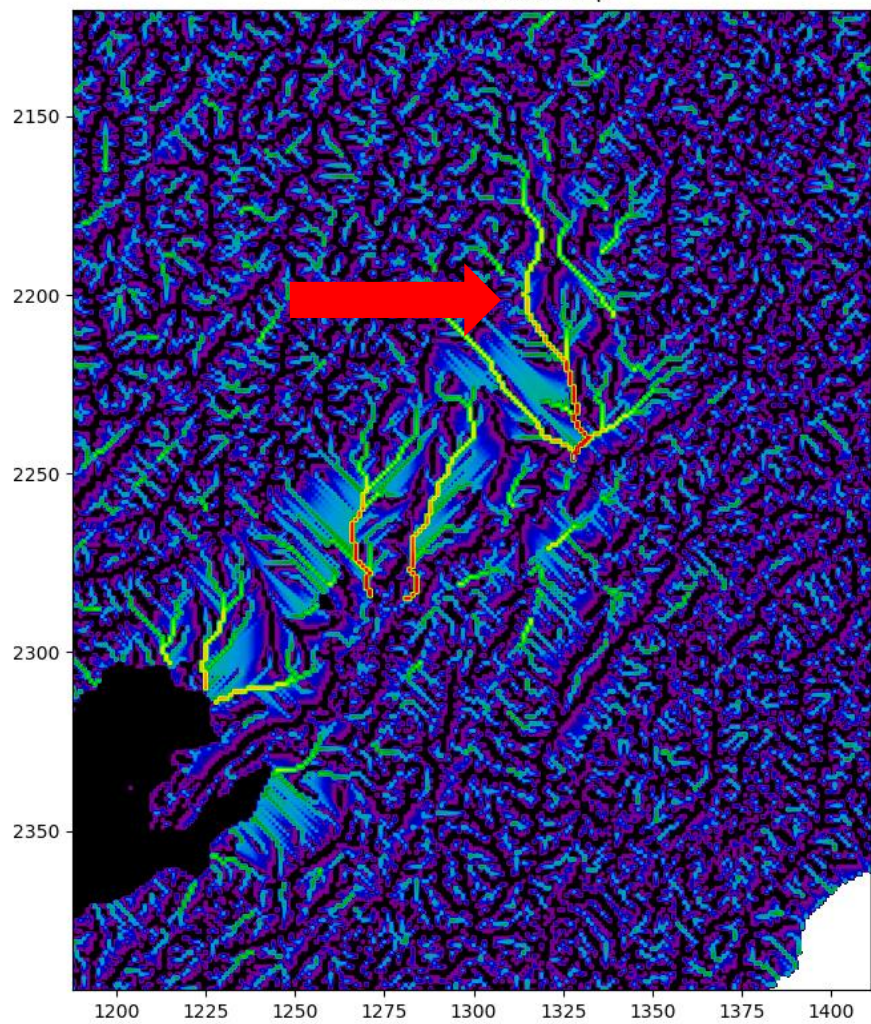
- One challenging aspect of response was the accumulation of trapped energy in harbours because of multiple events!
- How often does this happen in the catalogue and the real world?



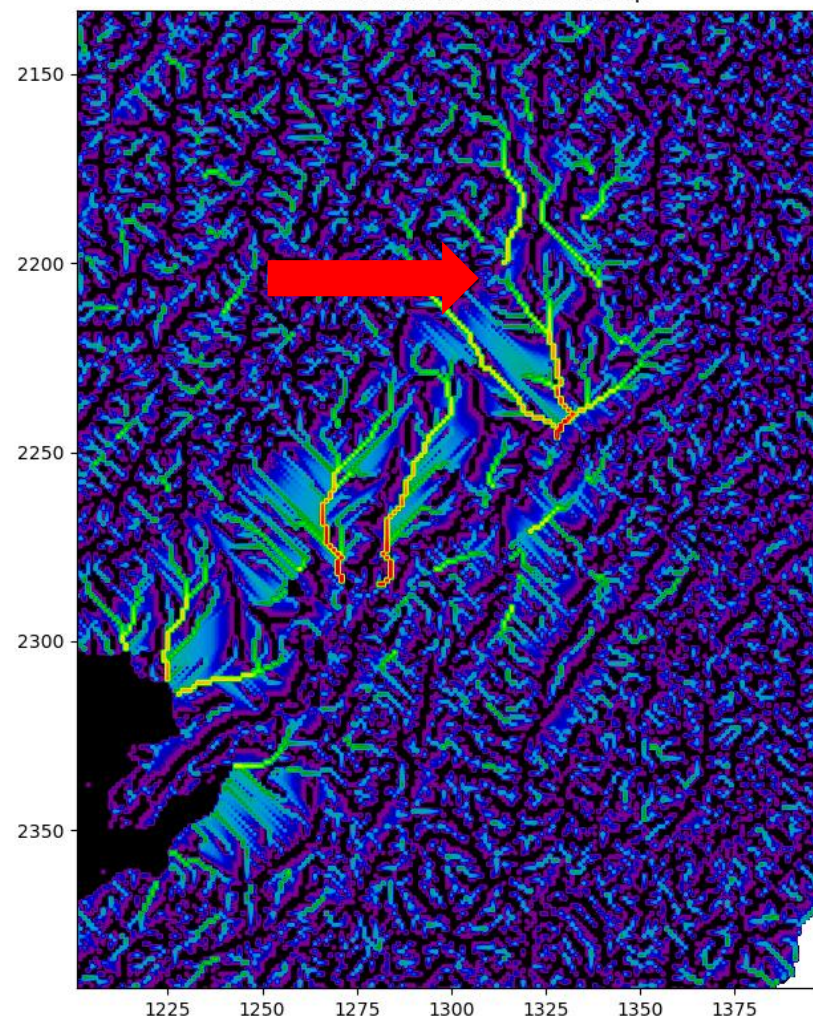
Summary

- Capturing the stochastic range of possible earthquakes opens up huge potential for improving resilience
 - Watch this space for
 - Next generation seismic and tsunami hazard
 - Critical testing of early warning algorithms
 - Better understanding of earthquake clustering and multi-fault rupture
 - Better models of co-seismic impacts including
 - Topographic amplification of ground motion and its impacts on landslide models
- Thanks for joining!
- Models of changes to surface and groundwater

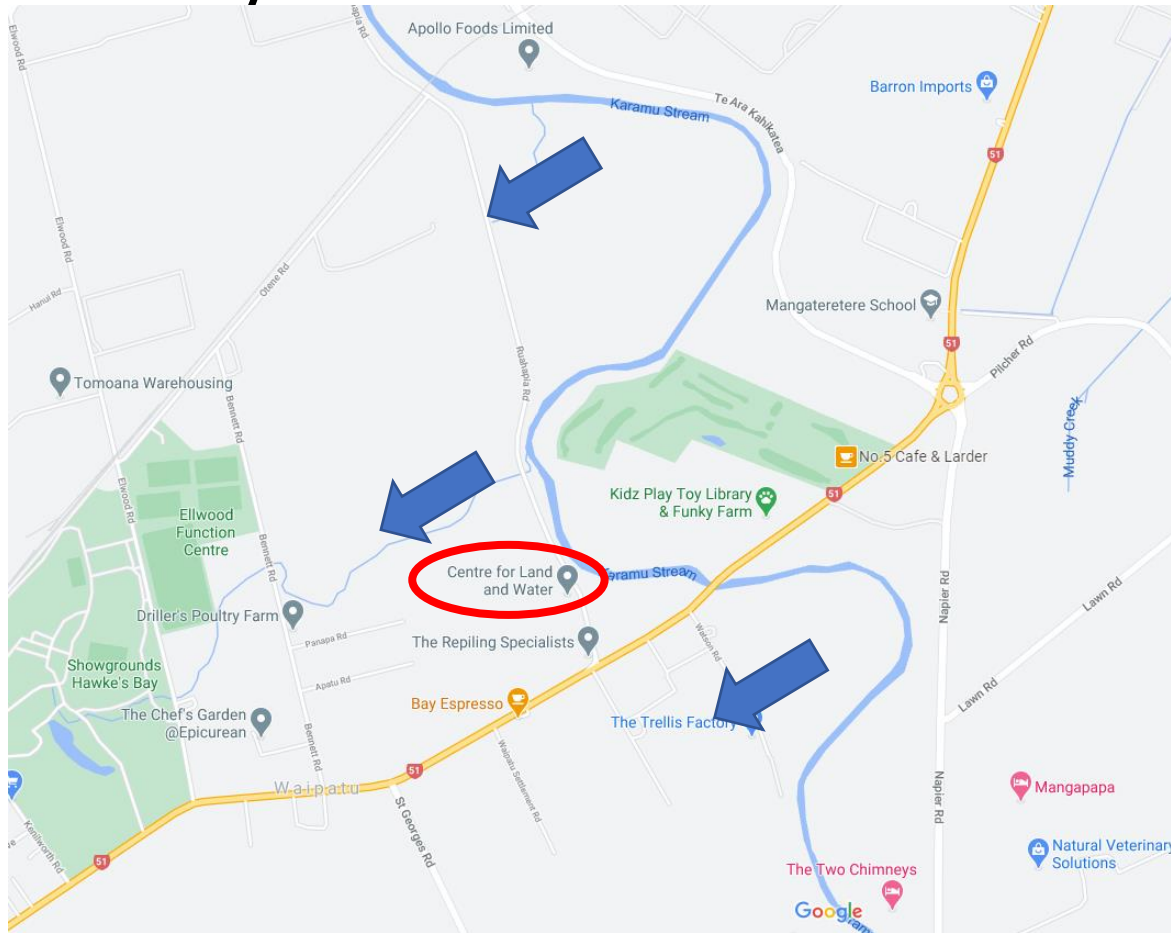
Initial accumulation map



Post-deformation accumulation map



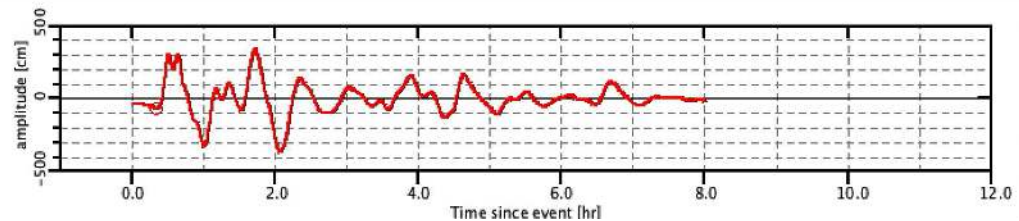
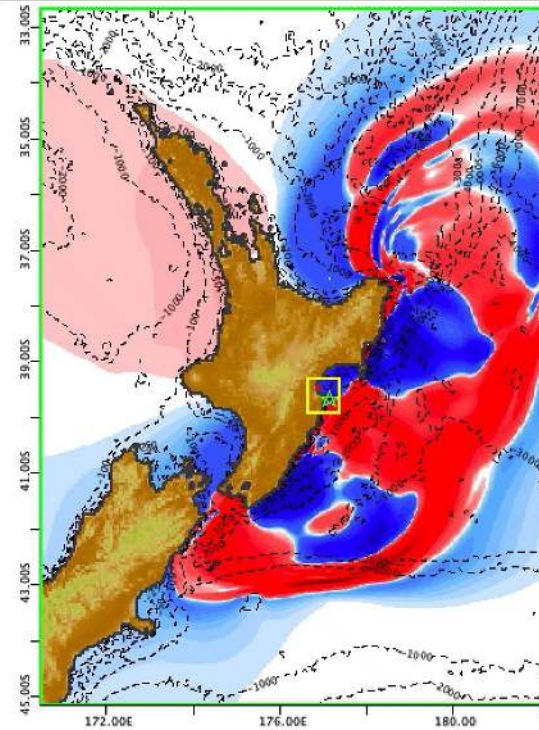
Hawke's Bay



Supplemental slide on w-phase at
short distances

Conclusions

- Purely from a monitoring perspective, instrumental cable would certainly help, but it's impacts aren't dramatic because of the (stream parallel) geometry
- Co-located sm and pressure sensors could probably help with removing seismic source contamination of tsunami measurements, subject to future work.



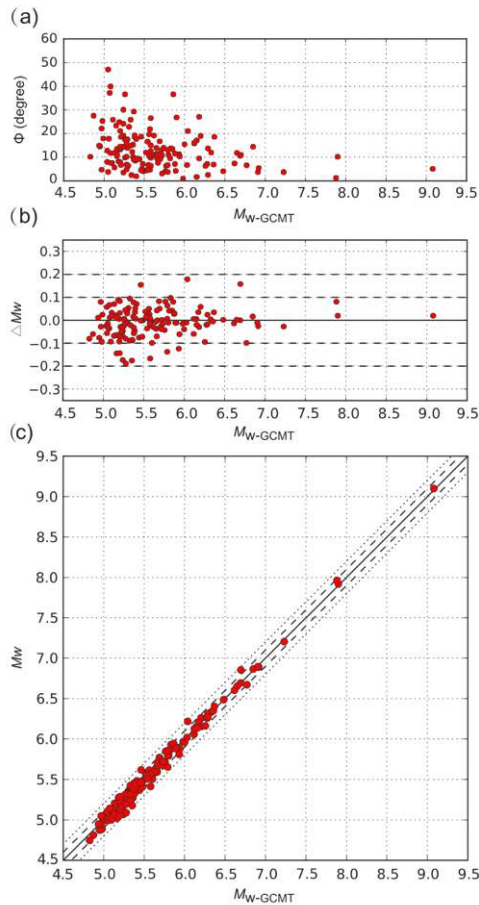


Figure 4. Comparison of W-phase and GCMT solutions obtained at $T_0 + 7$ min ($\Delta \leq 12^\circ$). (a) Comparison between W-phase and GCMT focal mechanisms. Φ is the angular difference between W-phase and GCMT focal mechanisms (see equation (3)). (b) Magnitude difference $\Delta M_W = M_W - M_{W-GCMT}$ between W-phase magnitude (M_W) and GCMT magnitude ($M_W - GCMT$). (c) Comparison between W-phase (M_W) and GCMT magnitude ($M_W - GCMT$).

- Left, the w-phase solution magnitudes available before 10 minutes compares really well with the global standard GCMT (within +/- Mw0.2).
- Right shows difference in epicentral locations between w-phase and GCMT. Difference in epicenter (top) and depth (bottom)
- Left and right plots based on 12 degrees of data (within 7 minutes). Table on bottom right shows what can be done with only 5degrees of data!

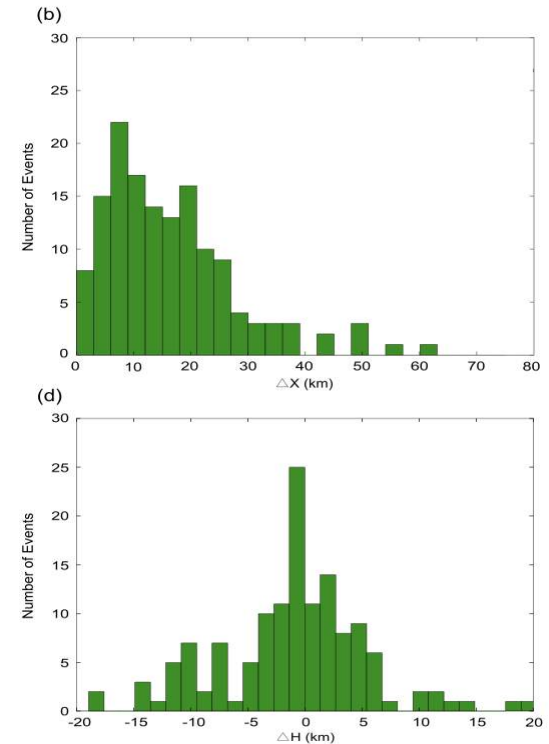


Table 2
Statistical Comparison of W-Phase and Global CMT Solutions Using Stations Within $\Delta \leq 5^\circ$ and $\Delta \leq 12^\circ$

Distance	Event number	$\langle \Delta M_W \rangle$	RMS (ΔM_W)	p ($ \Delta M_W \leq 0.1$)	p ($ \Delta M_W \leq 0.2$)	$\langle \Phi \rangle$	RMS (Φ)	p ($\Phi \leq 20^\circ$)	p ($\Phi \leq 30^\circ$)
$\Delta \leq 5^\circ$	106	0.02	0.06	90%	100%	14.4 °	16.9°	77%	95%
$\Delta \leq 12^\circ$	147	0.01	0.06	92%	100%	13.0 °	15.5°	85%	96%

Note. The number of solutions obtained is indicated in each case (event number) along with the mean and RMS values of the magnitude difference ($\Delta M_W = M_W - M_{W-GCMT}$) and focal mechanism angular difference (Φ). We also present the proportion (p) of solutions with $\Delta M_W \leq 0.1$, $\Delta M_W \leq 0.2$, $\Phi \leq 20^\circ$, or $\Phi \leq 30^\circ$.